

A Linear Relation between the Color Stretch s_{BV} and the Rising Color Slope $s_0^*(B - V)$ of Type Ia Supernovae

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 s_{BV} parameter is known to be tightly correlated with the peak luminosity, especially for *fast decliners* (dim Type Ia supernovae), and the luminosity correlation with s_{BV} is markedly better than with the classic light-curve width parameters such as $\Delta m_{15}(B)$. Thus, our new linear relation can be used to infer peak luminosity from s_0^* . Unlike s_{BV} (or $\Delta m_{15}(B)$), the measurement of $s_0^*(B - V)$ does not rely on a well-determined time of light-curve peak or color maximum, making it less demanding on the light-curve coverage than past approaches.

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Supporting material: figure set, machine-readable table

1. Introduction

As a supernova (SN) population, Type Ia supernovae (SNe Ia) show remarkable regularities in observed properties; in particular, their light curves follow a tight relation between peak luminosity and the decline rate, which is commonly referred to as the width–luminosity relation (WLR; see Phillips & Burns 2017 for a review). The empirical WLR extends from the most luminous SN 1991T-like SNe Ia (Filippenko et al. 1992b; Phillips et al. 1992; Ruiz-Lapuente et al. 1992a; Leibundgut et al. 1993; Turatto et al. 1996). The WLR not only offers important clues to understanding the physics of the SN Ia population, but also enables using SNe Ia as important cosmological distance indicators.

Pskovskii (1977, 1984) suggested the existence of the WLR for SNe Ia by using a post-peak slope parameter, β , to measure the light-curve decline rate. Its validity was called into question by some researchers owing to concerns over host-galaxy contamination to the SN flux measurements obtained with photographic plates (see, e.g., Boisseau & Wheeler 1991). Phillips (1993) established the WLR by using well-sampled light curves of nearby SNe Ia observed with charge-coupled devices and introduced the now-classic width parameter $\Delta m_{15}(B)$, which is the *B*-band magnitude difference between the magnitude at the time of peak brightness ($t_{\text{peak}}(B)$) and 15 days afterward. Later, other, similar width parameterizations such as the *stretch s* were introduced (Perlmutter et al. 1997), and there were also variants like x_1 in SALT2 (Guy et al. 2007) or Δ (Riess et al. 1996; Jha et al. 2007).

In order to accurately derive $\Delta m_{15}(B)$ directly from the light curve, good photometric coverage before $t_{\text{peak}}(B)$ to at least 15 days after $t_{\text{peak}}(B)$ is required. Since the light curves evolve slowly over the peak (varying by only ~0.1 mag in 1 week), an accurate peak-time determination is challenging if the light curve is not densely sampled around the peak. In practice, various template-fitting methods are often employed to derive $\Delta m_{15}(B)$ using well-sampled light-curve templates with known $\Delta m_{15}(B)$ (see, e.g., Hamuy et al. 1995, 1996; Prieto et al. 2006; Burns et al. 2011).

For low-luminosity, fast-declining SNe Ia, $\Delta m_{15}(B)$ is found to be a poor width discriminator, and the WLR using $\Delta m_{15}(B)$ shows large scatter for $\Delta m_{15}(B) \gtrsim 1.7$ mag (see, e.g., Burns et al. 2014; Gall et al. 2018). Similarly, the stretch method fails for fast decliners (see, e.g., Phillips & Burns 2017). From studying high-quality B - V color curves of SNe Ia observed by the Carnegie Supernova Project (CSP), Burns et al. (2014) found that fast-declining SNe Ia reach their reddest B - V color earlier than those with slower decline rates. To better characterize this, Burns et al. (2014) introduced the colorstretch parameter, s_{BV} , which is a dimensionless stretch-like parameter defined as $s_{BV} = t_{max}(B - V)/(30 \text{ days})$, where $t_{\max}(B - V)$ is time to the maximum (reddest) B - V color with reference to the *B*-band maximum. Since the B - V color quickly declines after reaching maximum, $t_{max}(B - V)$ corresponds to a sharp *break* in the B - V color curve (see Figure 1 for examples). Using s_{BV} as a proxy for decline rate (instead of $\Delta m_{15}(B)$), the scatter in the WLR significantly



Figure 1. B - V color curves of SNe Ia 2017ejb, 2017iyb, and 2017cbv. The data for SN 2017ejb is shifted downward by 0.25 mag to match the local minimum of B - V color, $(B - V)_{min}$, of the other two SNe. After the *B*-band peak, the B - V color curves have the typical evolution of first rising and then declining. The three SNe reach their maximum B - V colors at different times, which correspond to different s_{BV} values (see text for how they are measured). The rising slope seems to be correlated with the time of the maximum B - V color.

reduces at the low-luminosity end, and SNe Ia over the full range of luminosity lie on a tight and continuous correlation (Burns et al. 2018). Moreover, Ashall et al. (2020) found that combining s_{BV} with the time difference between *B*-band and *i*-band maxima is useful to discriminate between SN Ia subtypes.

Reducing the scatter in the WLR using s_{BV} not only has important implications for using SNe Ia as distance indicators, but also sheds new insight into the physics of WLRs. Wygoda et al. (2019) found that $t_{max}(B - V)$ corresponds to an abrupt change in the mean opacities due to ionization-state transitions of⁵⁶ Fe and ⁵⁶Co in the ejecta, while the timescale to reach the color maximum is determined by the ejecta ⁵⁶Ni column density, which sets the recombination time of Fe/Co ions.

To derive s_{BV} from light curves, it is required to measure not only $t_{max}(B - V)$, but also, like $\Delta m_{15}(B)$, a precise estimate of $t_{peak}(B)$. In this work, we report the finding of a linear relation between s_{BV} and the rising linear slope of the B - V color curve of SNe Ia, which is defined as $s_0^*(B - V)$ by us, using the CNIa0.02 sample (Chen et al. 2022). As a proxy for light-curve width and in turn, the peak luminosity via the WLR, $s_0^*(B - V)$ has the merit of being less demanding on light-curve coverage.

It is noteworthy that the Color-MAGnitude Intercept Calibration (CMAGIC) method developed by Wang et al. (2006) and Conley et al. (2006) shares the same advantage of being less demanding on light-curve coverage when using the WLR. The CMAGIC method also exploited the color curves of SNe Ia, and it was built on the empirical linear relation between

 Table 1

 Light-curve Parameters of SNe Ia in the CNIa0.02 Sample

 $\Delta m_{15}(B)$

SN	t _{peak} (B) (MJD)	$\begin{array}{c} \Delta m_{15}(B) \\ (\text{mag}) \end{array}$	<i>s</i> ₀	<i>s</i> ₁	S_{BV}	s_0^*
2016bfu	57469.7 ± 0.6	1.81 ± 0.09	0.109 ± 0.019	-0.0129 ± 0.0053	0.49 ± 0.09	0.076 ± 0.012
2016blc	57489.8 ± 1.1	0.99 ± 0.13	0.050 ± 0.005	-0.0099 ± 0.0014	1.08 ± 0.09	0.048 ± 0.003
2016fff	57630.0 ± 0.2	1.81 ± 0.06	0.082 ± 0.009	-0.0119 ± 0.0039	0.67 ± 0.09	0.076 ± 0.002
2016fej	57635.5 ± 0.7	0.89 ± 0.08	0.049 ± 0.002	-0.0125 ± 0.0007	1.07 ± 0.04	0.049 ± 0.003
2016gtr	57667.1 ± 0.9	0.94 ± 0.11	0.045 ± 0.005	-0.0204 ± 0.0068	1.18 ± 0.07	0.043 ± 0.001

(This table is available in its entirety in machine-readable form.)

color and magnitude (e.g., B - V versus B magnitude) during post-peak phases whose slope has a nearly constant value over a wide range of light-curve widths (Wang et al. 2003).

2. Light-curve Analysis

Here, we analyze the *B*- and *V*-band light curves presented by Chen et al. (2022). We include SNe Ia ranging from the most luminous end (i.e., SN 1991T-like) to the least luminous end (i.e., SN 1991bg-like) in the analysis, while we exclude five objects that do not belong to the complete sample of CNIa0.02 (see Appendix D of Chen et al. 2022 for details regarding those excluded objects). In order to obtain accurate s_{BV} measurements, we need to reliably infer the time of the *B*band peak, $t_{peak}(B)$, and the time of maximum B - V color, $t_{max}(B - V)$. We discuss below how we select the SNe used in the analysis.

First, the *B*-band light curves need to have coverage around the peak to infer $t_{peak}(B)$. We adopt the criterion of having at least 3 epochs within 6 days of the peak and at least 4 points within 10 days of the peak. Throughout the paper (unless otherwise specified), $t_{peak}(B)$ is used as the reference time. It is obtained with the Gaussian process method if pre-peak data are available; otherwise, it is derived from template fitting using SNooPy (Burns et al. 2011). We list the derived $t_{peak}(B)$ and $\Delta m_{15}(B)$ values in Table 1.

Next, we analyze the B - V color curves for all remaining SNe to infer s_{BV} , and the SNe without data late enough to derive $t_{max}(B - V)$ are excluded from the analysis. To obtain reliable s_{BV} values, we impose the following selection criteria: (1) the B - V color curve needs to have at least 4 data points covering no less than half of the time range between $t_{peak}(B)$ and $t_{max}(B - V)$; and (2) after $t_{max}(B - V)$, there need to be at least 2 data points spanning more than 5 days, and the last data point needs to be at least ~10 days after $t_{max}(B - V)$. The phase of the B - V color curve is corrected for time dilation. Since all targets have low redshifts, the K-correction is negligible for our analysis and thus is not applied.

In Figure 1, we show the B - V color curves of three SNe Ia with $s_{BV} = 0.41$, 0.89, and 1.11, respectively. After $t_{\text{peak}}(B)$, the B - V color curve soon enters a linear rise phase (hence, becoming redder), followed by a linear decline (becoming bluer) after $t_{\text{max}}(B - V)$. The rising slope and $t_{\text{max}}(B - V) - t_{\text{peak}}(B)$ seem to correlate with each other. It has been recognized previously that fast decliners tend to have faster post-peak B - Vcolor evolution compared to those with higher luminosity (see, e.g., Hoeflich et al. 2017). Here for the first time we measure the relevant light-curve parameters to quantitatively study the observed correlation. In the following, we describe how we measure the parameters from the color curves. We fit the time evolution of the B - V color since the onset of the post-peak linear rise phase based on Equation (2) of Burns et al. (2014). The model has the form

$$y(t) = \frac{1}{2}(s_0 + s_1)t + \frac{\tau}{2}(s_1 - s_0)\ln\left[\cosh\left(\frac{t - t_h}{\tau}\right)\right] + c,$$
(1)

where t is the rest-frame time relative to $t_{\text{peak}}(B)$, s_0 and s_1 , respectively, characterize the rising and declining slopes, τ is the transition timescale indicating how fast the color curve changes from the rising to the declining slope, and $t_{\rm h}$ is the time when the derivative of y(t) is equal to the averaged value of the initial and final slopes (i.e., $y'(t_h) = (s_0 + s_1)/2$). We drop the last polynomial term on the right-hand side in Equation (2) of Burns et al. (2014), since that term is used for modeling the color curve prior to the onset of the linear rise phase. In addition, we correct a typographical error in the first term (correcting $(s_0 - s_1)/2$ of Burns et al. 2014 to $(s_0 + s_1)t/2$). Note that in this model, the rising and declining sides are not strictly linear with time, and s_0 and s_1 (respectively) are only supposed to be close to the first derivatives for most parts of the two sides. We illustrate the example of SN 2017cbv in Figure 2, in which the best-fit model is shown with a red line. The time of the maximum B - V color where $y'(t_{\max}(B - V)) = 0$, as indicated by the vertical line in Figure 2, is^{36}

$$t_{\max}(B - V) = \frac{\tau}{2} \ln\left(-\frac{s_0}{s_1}\right) + t_{\rm h}.$$
 (2)

We note that the phase when the linear rise starts, t_s , is correlated with $t_{max}(B - V)$. SNe Ia with higher s_{BV} enter the linear phase at a later time. We adopt an empirical estimate of $t_s = 0.3 t_{max}(B - V) - 2$ days after $t_{peak}(B)$ as the start phase for our fitting. The adopted end phase for fitting is 90 days after $t_{peak}(B)$. Since $t_{max}(B - V)$ is needed to derive the phase range used for the fit, we iteratively determine this phase range with an initial range of [5, 90] days.

We fit the B - V color curves using the Markov Chain Monte Carlo (MCMC) method to get the best-fit values of all the parameters in Equation (1). Equation (2) is used to determine $t_{max}(B - V)$ and then $s_{BV} = t_{max}(B - V)/30$. The derived s_{BV} , s_0 , and s_1 parameters for 86 SNe Ia with their uncertainties are given in Table 1.

 $[\]frac{36}{Note}$ Note that $t_{\rm h}$ was inaccurately regarded as the time of B - V maximum by Burns et al. (2014) (C. Burns 2023, private communications).



Figure 2. B - V color curve of SN 2017cbv with best-fit results shown as an example of the procedure described in this paper. The observed data are shown as black dots and the best-fit model with Equation (1) is shown in red. The black dashed lines indicate the rising slope s_0 and declining slope s_1 from Equation (1). The vertical black line marks the time of the reddest B - V color. The direct linear fit to get the rising slope $s_0^*(B - V)$ is shown as the blue line. The stent of the blue line indicates the range of the linear region defined by $[t_s, t_e] = [0.3 t_{max}(B - V) - 2, 0.9 t_{max}(B - V)]$. (The complete figure set with a simplified version of the plots for all 86 objects used to derive the linear relation is available in the online journal.)

(The complete figure set (86 images) is available.)

In the above MCMC fitting of the B - V color curve, we applied uniform priors for all parameters. We found that the best-fit value of τ is highly sensitive to its prior. Our work was initially motivated by the apparent correlation between s_{BV} and s_0 . However, after further investigation, we found that s_0 is also correlated with τ ; therefore, the best-fit value of s_0 from the MCMC fitting is affected by the prior that we placed on τ . The reason for the effect of τ on s_0 can be understood by examining the time derivative of Equation (1),

$$y'(t) = \frac{s_0 + s_1}{2} + \frac{s_1 - s_0}{2} \tanh\left(\frac{t - t_h}{\tau}\right).$$
 (3)

Clearly the deviation of y'(t) from a constant (i.e., as followed from a linear model with respect to t) in the rising part of the model depends on τ . In practice, the derived values of τ often have relatively large uncertainties, and they also correlate with s_{BV} , making it difficult to establish a clear-cut correlation between s_0 and s_{BV} .

Instead of using s_0 defined in Equation (1), we measure the rising slope by directly fitting a linear model $y(t) = s_0^* t + c^*$ to the rising part of the color curve. To do so, we need to determine a phase range $[t_s, t_e]$ during which the color curve is well characterized by a linear model. As can be seen from Figure 1, both the beginning and end phases of the linear phase seem to be correlated with the time of maximum B - V color. Therefore, the values of t_s and t_e depend on $t_{max}(B - V)$. After some experimentation, we find that the range defined with $t_s = 0.3 t_{max}(B - V) - 2$ and



Figure 3. Correlation between the color-stretch parameter, s_{BV} , and the rising color slope, s_0^* , of the B - V color. All of the measurements for 86 SNe Ia in Table 1 are shown here. The blue line indicates the best linear fit and the shaded range indicates the 95% confidence region for the fit.

 $t_e = 0.9 t_{\text{max}}(B - V)$ can be well characterized by a linear model for SNe Ia with a broad range of s_{BV} . The best-fit linear model within such a range is shown as a blue line in Figure 2. We exclude from the analysis SNe Ia with fewer than 3 points in the B - V color curve within $[t_s, t_e]$. In the end, 86 SNe Ia meet all of the above criteria. The directly measured rising color slope parameters, s_0^* , are provided in Table 1. By comparing the values of s_0 and s_0^* , we find that s_0 tends to be larger than s_0^* .

3. Results

As shown in Figure 3, we clearly see that s_0^* and s_{BV} are linearly correlated; the linear correlation coefficient is r = -0.90, which is highly significant. We perform a linear fit with the Orthogonal Distance Regression method (Boggs et al. 1987) implemented in the Python package Kapteyn (Terlouw & Vogelaar 2016). The best-fit linear model between s_0^* and s_{BV} accounting for uncertainties yields

$$s_{BV} = 0.919(0.008) - 13.67(0.61) \times (s_0^* - 0.057).$$
 (4)

The uncertainties given in the parentheses are obtained by scaling the measurement errors of s_0^* and s_{BV} to have $\chi^2/\text{dof} = 1$, where "dof" is the number of degrees of freedom. The residuals to this best-fit linear model have a scatter of 0.093 in s_{BV} , comparable with the median s_{BV} measurement uncertainty of 0.082. The uncertainties in the s_0^* inference also affect how tight the derived relation is. CNIa0.02 light curves were observed with multiple instruments having various natural-filter systems, which may also introduce systematic differences in the B - V color curves that contribute to the scatter seen here. This linear relation between s_{BV} and s_0^* suggests that s_0^* can be used to infer s_{BV} . As shown in the left panel of Figure 4, we compare

As shown in the left panel of Figure 4, we compare $s_0^*(B - V)$ with $\Delta m_{15}(B)$ using our sample. Similar to the well-known trends (Burns et al. 2014) when comparing s_{BV} and $\Delta m_{15}(B)$ (right panel of Figure 4), there is a linear correlation



Figure 4. Comparisons of $s_0^*(B - V)$ (left) and s_{BV} (right) with respect to $\Delta m_{15}(B)$. For SNe Ia with $\Delta m_{15}(B) < 1.7$ mag (vertical dashed lines), both s_0^* and s_{BV} are linearly correlated with $\Delta m_{15}(B)$ (the black lines in both panels), whereas there is a large scatter for fast decliners with $\Delta m_{15}(B) > 1.7$ mag.

for SNe Ia with $\Delta m_{15}(B) < 1.7$ mag; however, for those with $\Delta m_{15}(B) > 1.7$ mag, there is large scatter.

The inference of s_0^* has comparative merit over s_{BV} or $\Delta m_{15}(B)$ in the data-coverage requirements. Measuring s_{BV} depends on determining two critical timing parameters, $t_{\text{peak}}(B)$ and $t_{\max}(B - V)$. The measurement of $\Delta m_{15}(B)$ is also highly sensitive to how well $t_{peak}(B)$ is determined. By comparison, deriving s_0^* is simply measuring a slope, which does not require determining either of those two timings; instead, s_0^* can be determined for an SN which is not observed around peak lacks brightness and/or coverage at later times around $t_{\max}(B - V)$.

4. Measurement Procedure

In practice, when either $t_{\text{peak}}(B)$ or $t_{\max}(B - V)$ is absent, it is not possible to use the phase range of $([t_s = 0.3 t_{\max}(B - V) - 2, t_e = 0.9 t_{\max}(B - V)])$ with respect to $t_{\text{peak}}(B)$ to fit s_0^* . Figure 5 shows light curves with different temporal coverages. Below we provide a practical procedure to measure s_0^* for such light curves.

- 1. If the B-band light curve around the peak is available to measure $t_{\text{peak}}(B)$, but there is no sufficiently late observation to determine the break time in the B V color curve. First, start by fitting all data after $t_{\text{peak}}(B)$ to get the initial s_0^* , and then use Equation (4) to estimate s_{BV} and subsequently $t_{\max}(B V) = s_{BV} \times 30$ days. Then use the range of $[0.3 t_{\max}(B V) 2, 0.9 t_{\max}(B V)]$ for the next fitting and iteratively repeat this process until it converges. See the left column of Figure 5 for some examples in this category.
- 2. If the B V color curve around the break time is available to measure the time of maximum B - V color, but there is no B-band coverage over the peak to measure $t_{peak}(B)$. In this case, without the reference time of $t_{peak}(B)$, a new reference time of t_{break} (measured as the time of maximum B - V color) will be used. First, start by fitting all data before t_{break} to get the initial s_0^* , and use Equation (4) to estimate $t_{max}(B - V)$. Then use the range from 0.7 $t_{max}(B - V) + 2$ to 0.1 $t_{max}(B - V)$ days before t_{break} for the next fitting and iteratively repeat this process until it converges. See the middle column of Figure 5 for some examples in this category.
- 3. If neither the B-band peak nor the break part in the B V color curve is available. The value of s_0^* can be estimated by fitting the available color data that are consistent with



Figure 5. Examples of *B* and *V* light curves as well as B - V color curves with different temporal coverages as listed in Section 4. SNe Ia in the left column (SNe 2016euj, 2018hsa, and 2019khf) belong to the category that has the measurement of $t_{peak}(B)$ but no $t_{max}(B - V)$, and the phase of these SNe is relative to $t_{peak}(B)$. SNe Ia in the middle column (SNe 2017gxq, 2018jmo, and 2019lt) have the time of the maximum $B - V \operatorname{color}(t_{break})$ but no $t_{peak}(B)$, and the phase of these SNe is relative to t_{break} . SNe Ia in the right column (SNe 2016fob, 2017fvl, and 2018cqj) have neither $t_{peak}(B)$ nor $t_{max}(B - V)$, and the phase of these SNe is relative to the time of the first B - V data point. For each object, the upper plot shows the *B*-band (in blue color) and the *V*-band (in red color) light curves, and the lower plot displays the B - V color curve (black dots), the best-fit linear model (blue line), and the corresponding $s_0^*(B - V)$. The extent of the blue line indicates the range of data used to calculate the rising color slope according to the procedures in Section 4.

a straight line, but this may introduce systematic uncertainties owing to the uncharacterized fitting range. See the right column of Figure 5 for some examples in this category.

5. Summary and Discussion

In summary, we find a linear relation between the colorstretch parameter (s_{BV}) and the rising color slope $(s_0^*(B - V))$ of the B - V color after the *B*-band peak, and this relation is applicable to the whole s_{BV} range of SNe Ia. With this linear relation, $s_0^*(B - V)$ can be used to infer s_{BV} , which is known to be tightly correlated with the peak luminosity; in comparison, obtaining $s_0^*(B - V)$ requires less demanding light-curve coverage than s_{BV} . What also distinguishes $s_0^*(B - V)$ from $\Delta m_{15}(B)$ and its variants (e.g., Δm_8 , Δm_{30} ; Sharon & Kushnir 2022) is that measuring $s_0^*(B - V)$ does not necessarily need coverage over the light-curve peak. Therefore, applying $s_0^*(B - V)$ can broaden the capacity of estimating the peak luminosity, which is a key parameter of SNe Ia. It will be interesting to study whether s_0^* measured in a color other than B - V has a similar correlation with s_{BV} . In a limited check we perform using the multiband light curves from the third photometry data release of the first stage of the Carnegie Supernova Project (CSP-I; Krisciunas et al. 2017), we find no good correlation between $s_0^*(g - r)$ and s_{BV} (or s_{gr}). The lack of a good correlation between $s_0^*(g - r)$ and s_{BV} (or s_{gr}) might be related to the emergence of secondary bumps in the *r*-band light curves of some SNe Ia starting ~15 days after the *B*-band peak (see, e.g., Papadogiannakis et al. 2019).

Another future research direction is to study the underlying physical mechanism of the $s_{BV}-s_0^*(B-V)$ relation, and it remains to be seen whether it can be interpreted by the same physical process for the WLR via s_{BV} (Wygoda et al. 2019) or some other aspect of SN physics.

As shown by Burns et al. (2014, 2018), the WLR via s_{BV} has been successfully used to accurately measure the Hubble constant. Owing to its correlation with s_{BV} , s_0^* has the potential to be used for cosmology as an alternative proxy of light-curve width parameter, and since relatively sparse light curves are common for high-*z* SNe Ia used in cosmological studies, s_0^* may be particularly promising because it is less demanding on light-curve coverage. Further investigations will be needed to establish whether s_0^* will be viable for precision cosmology.

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