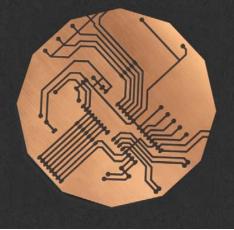
# An Analytical Method for Centroid Computing and Its Application in Wireless Localization

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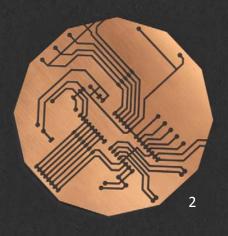




#### **Outline**

- Background
- Centroid Computing
- Proposed Analytical Approach
  - Special case
  - General case
- Application in Wireless Localization
- Conclusion

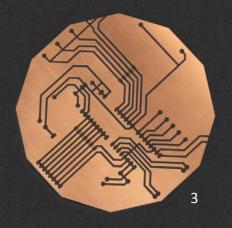




# Background

- Wireless Sensor Networks
  - Wide application scenarios
  - Omni-directional transmission gives a coverage roughly like a circle
  - Scarce power resources, usually operating on batteries
- Wireless localization Technique
  - Location information is necessary for meaningful data collection.
  - Localization Techniques
    - Region-based
    - Range-based



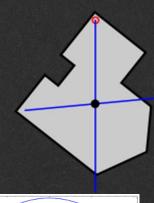


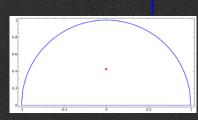
# **Centroid Computing**

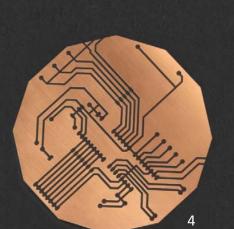
- Centroid
  - the point at which a cardboard cut-out of the region could be perfectly balanced on the tip of a pencil, with the assumption of uniform density and uniform gravitational field.
- How to locate the centroid?
  - Plumb line method
  - Geometric decomposition method
  - By integral formula

Source: http://en.wikipedia.org/wiki/Centroid

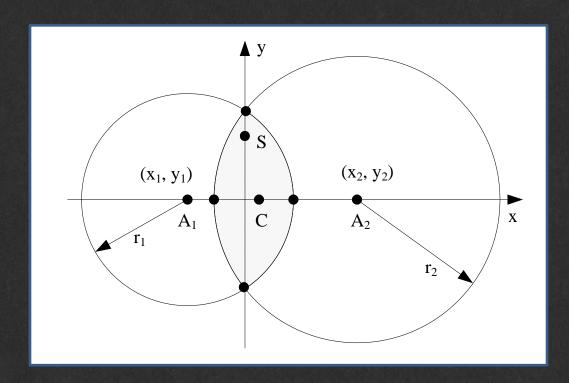






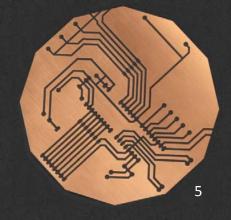


# **Centroid Computing**



It is not difficult to compute the centroid of a half circle. But how about the centroid for the overlapped region of two intersecting circles (see the figure on the left)?







# Proposed Analytical Method

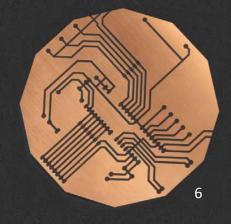
Overlapped area of two intersecting circles

$$\begin{cases} (x - x_1)^2 + (y - y_1)^2 = r_1^2, & (x - x_2)^2 + (y - y_2)^2 = r_2^2 \\ (x_S - x_1)^2 + (y_S - y_1)^2 \le r_1^2, & (x_S - x_2)^2 + (x_S - y_2)^2 \le r_1^2 \\ |r_1 - r_2| \le \sqrt{(x - x_1)^2 + (y - y_1)^2} \le r_1 + r_2 \end{cases}$$

By integration

$$(\overline{x}, \overline{y}) = \left(\frac{\iint_{R} x dx dy}{\iint_{R} dx dy}, \frac{\iint_{R} y dx dy}{\iint_{R} dx dy}\right)$$

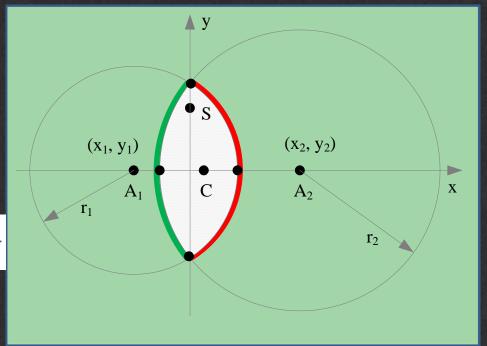




# **Analytical Solution for Special Case**

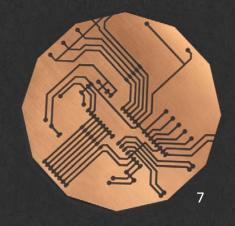
$$f(x_2) = \pm \sqrt{r_2^2 - (x - x_2)^2}$$
, for left boundary

$$f(x_1) = \pm \sqrt{r_1^2 - (x - x_1)^2}$$
, for right boundary



$$\overline{x} = \frac{\int_{x_2 - r_2}^{0} 2x \sqrt{r_2^2 - (x - x_2)^2} dx + \int_{0}^{x_1 + r_1} 2x \sqrt{r_1^2 - (x - x_1)^2} dx}{\int_{x_2 - r_2}^{0} 2\sqrt{r_2^2 - (x - x_2)^2} dx + \int_{0}^{x_1 + r_1} 2\sqrt{r_1^2 - (x - x_1)^2} dx}$$





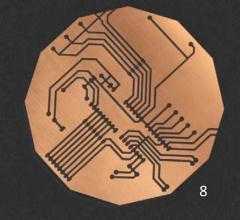
# **Analytical Solution for Special Case**

$$\overline{x} = P/Q$$

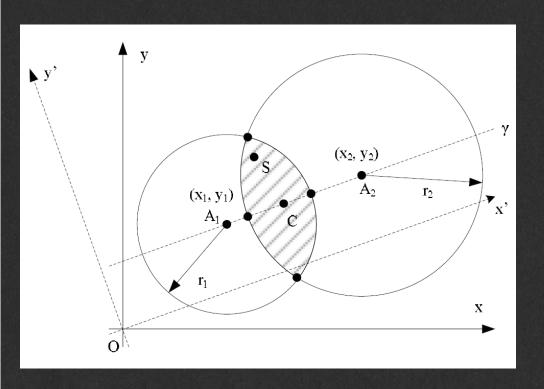
$$P = \frac{\pi}{4} (x_1 r_1^2 + x_2 r_2^2) + \left(\frac{r_1^2}{3} + \frac{x_1^2}{6}\right) \sqrt{r_1^2 - x_1^2}$$
$$-\left(\frac{r_2^2}{3} + \frac{x_2^2}{6}\right) \sqrt{r_2^2 - x_2^2} + \frac{r_1^2 x_1}{2} \sin^{-1}\left(\frac{x_1}{r_1}\right) - \frac{r_2^2 x_2}{2} \sin^{-1}\left(\frac{x_2}{r_2}\right)$$

$$Q = \frac{\pi}{4} (r_1^2 + r_2^2) + \frac{x_1}{2} \sqrt{r_1^2 - x_1^2} - \frac{x_2}{2} \sqrt{r_2^2 - x_2^2}$$
$$+ \frac{r_1^2}{2} \sin^{-1} \left(\frac{x_1}{r_1}\right) - \frac{r_2^2}{2} \sin^{-1} \left(\frac{x_2}{r_2}\right)$$





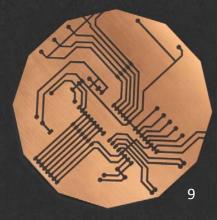
#### **General Case**



For the general case where the centres of two intersecting circles are not on the same axis, we need to:

- 1) Perform axis rotation
- 2) Perform axis shifting
- 3) Compute the centroid using the solution from special case
- 4) Perform axis shifting
- 5) Perform axis rotation and then obtain the analytical solution



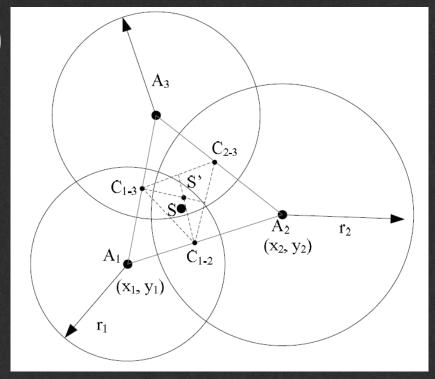


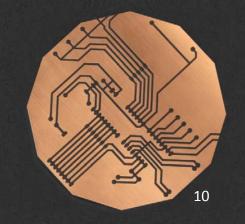
### Application of Analytical Centroid Computing

- Centroid-Based Localization (CBL)
  - Anchors deployment
    - e.g., A<sub>1</sub>, A<sub>2</sub>, A<sub>3</sub>
  - Beacon frames broadcast
  - Beacon frames synthesis
    - Compute C<sub>1,2</sub>, C<sub>1,3</sub>, C<sub>2,3</sub>
  - Location estimation
    - Estimate sensor location for S

$$S': (x_{s'}, y_{s'}) = \left(\frac{x_{C_{1-2}} + x_{C_{1-3}} + x_{C_{2-3}}}{3}, \frac{y_{C_{1-2}} + y_{C_{1-3}} + y_{C_{2-3}}}{3}\right)$$

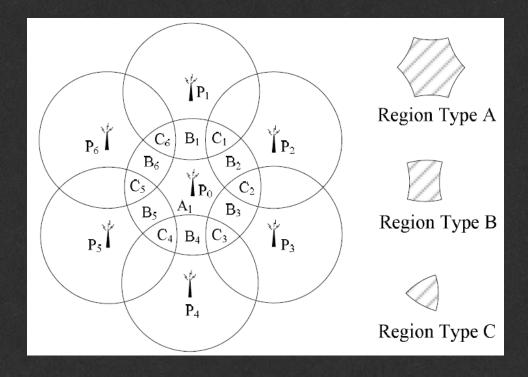




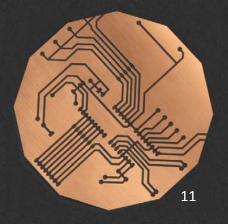


# Region-Based Localization

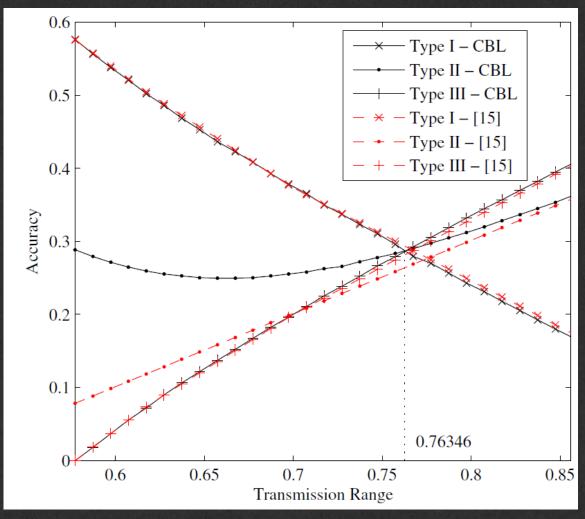
 To facilitate comparison, existing Region-Based Localization (RBL) was revisited here.



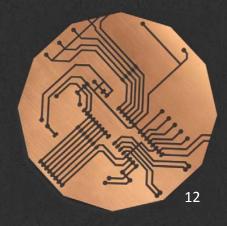




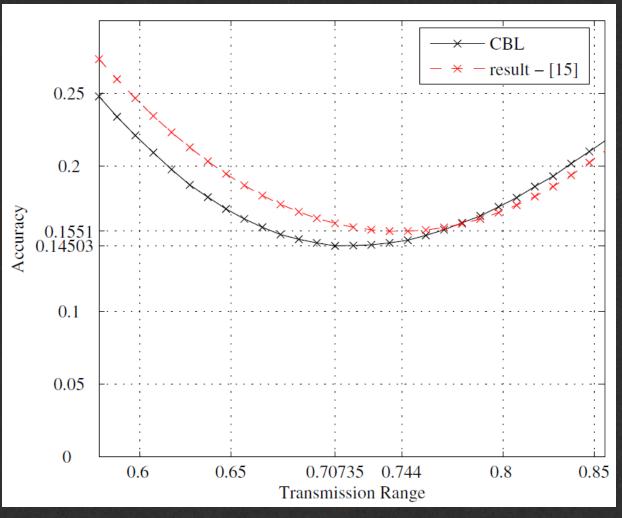
# Worst-case Performance Comparison



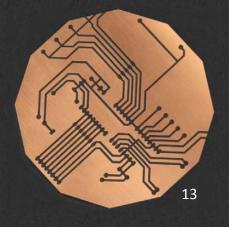




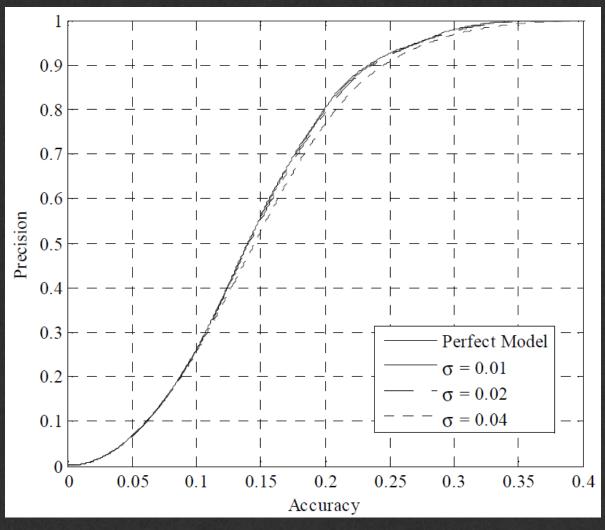
# Average Accuracy Comparison



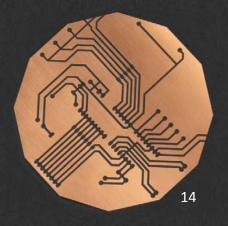




# Effect of Mismatch in Anchor Transmission Power Levels







#### Conclusion

- An analytical approach of computing the centroid for the overlapped area of any two intersecting circles was presented.
- Centroid Based Localization (CBL) was proposed and its performance was compared with existing region based localization technique through computer simulations.
- CBL is able to improve localization accuracy while reducing transmission power of anchor nodes.
- The effect of power mismatch was also studied.



#### A&P

# Thank you for your attention!

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